

Study of the surface quality of carbon fiber–reinforced thermoplastic matrix composite (CFRTP) machined by abrasive water jet (AWJM)

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Abstract

Carbon fiber-reinforced thermoplastics (CFRTP) have great interest nowadays due to their excellent mechanical properties and lightness. However, in opposition to thermoset matrix composites, there is a lack in the research about machining processes of these materials. Their low glass transition temperature is a handicap when conventional machining is used. An alternative is abrasive water jet machining (AWJM) because it does not cause thermal damage. However, the surface quality produced by this process must be studied and related to the cutting parameters. This article studies the surface quality generated by water jet machining in a low melting point thermoplastic matrix composite material. The kind of thermoplastic used is a TPU (polyurethane). The combination of a high-strength material (carbon fiber) with a low-strength material (thermoplastic matrix) makes machining difficult and can generate a poor surface finish. The influence of cutting parameters has been evaluated through an ANOVA analysis. A mathematical model that relates the surface quality with the cutting parameters has been established by means of a response surface methodology (RSM). The combination of a hydraulic pressure of 250 MPa with a traverse speed of 300 mm/min and an abrasive mass flow of 170 g/min produces the best surface quality. Finally, the main flaws when CFRTP is water jet machined have also been identified.

Keywords AWJM · CFRTP · Surface quality · RSM · ANOVA · C/TPU

1 Introduction

Most literature about machining of composite materials is focused in carbon fiber-reinforced plastics with thermoset matrix (CFRP), mainly due to the fact that they are difficult to machine materials [1–3]. CFRP materials stand out for their excellent weight/mechanical property ratio. This makes them strategic materials for the aeronautical sector in order to reduce the final weight of the aircraft.

However, carbon fiber-reinforced thermoplastics (CFRTP), a composite material with thermoplastic matrix, are being considered as an alternative in recent years [4–6]. Its manufacturing process differs from thermosets. This is based on the fabrication of stacks by thermoforming. Nevertheless, high temperatures are generated during the process. Thermoplastic polymers do not release gases or water vapor if they are correctly dried before processing [7]. As well, once joining, CFRTPs have a high impact resistance, excellent chemical resistance, and a long service life. Also, they have an excellent weight/mechanical properties ratio, and high recycling efficiency. In addition, high-performance

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thermoplastics can achieve higher operating temperatures than thermosets [8, 9]. In terms of manufacturing processes, they can achieve lower process times than CFRPs [9, 10]. Therefore, CFRTPs are being considered as strategic materials for the future development of the transport sector. These materials can minimize the final weight of the structure, which both reduce CO₂ emissions [10].

These materials must be machined to obtain a final geometry, which usually have to satisfy high quality requirements. There are few scientific literatures about the machining of CFRTPs, and it is mainly focused in conventional operations such as drilling, milling, or disk cutting [11–13].

Conventional machining operations can produce several defects, caused by high process temperatures. In addition, process rates can be unproductive resulting in low material removal rates. This may require specific geometries to avoid defects such as internal delaminations or matrix degradation. The low melting temperatures of thermoplastic polymers usually result in matrix losses, producing a defect denoted as burr according to [4]. This fact, together with the abrasive wear generated by carbon fibers, makes the conventional machining of CFRTPs a difficult task.

An interesting alternative process is abrasive water jet machining (AWJM), a very useful non-conventional machining for the cutting of dissimilar materials at once [14–16]. It is a flexible process that generates low thermal damage to the machined surface as there is no continuous tool-material contact along the machining process [17–19]. Compared to conventional processes such as milling, abrasive particles are used in water jet machining. These particles have cutting edges that allow the machining of the material by overlapping of small impacts that deform the material. At each instant, a quantity of abrasive particles travels in the water jet in order to perform the cut. In addition, although there is wear in the elements that make up the AWJM equipment (nozzle and mixing tube), this is much less than that produced in cutting tools in conventional processes.

Also, it is a process that can generate more reduced forces during the machining process than those resulting from processes such as milling [20].

As there is little literature focused on abrasive water jet machining in thermoplastic matrix composite materials, research on thermoset composite materials is considered. Due to their nature, the results obtained can be taken as reference.

Mayuet et al. [21] developed a study about the type of defects caused in the water jet machining of CFRP. It is composed by a 0/90° thermoset composite material with a thickness of 4 mm. This research shows that the main defect caused was delaminations, which can be reduced by a combination of high hydraulic pressure and high abrasive mass flow.

Another relevant defect is the opening of the water jet channel, called taper angle. This defect is related to the transverse traverse speed and the loss of kinetic energy in the

cutting channel [16, 22, 23]. In this line, one of the main requirements when a machining process is industrialized is the surface quality. High surface quality requirements can be reached in AWJM by applying high hydraulic pressures, increasing the water jet kinetic energy and reducing its divergence. Ming et al. [24] have studied the influence of cutting parameters in the surface quality through response surface methodology, obtaining a mathematical model that allows to predict optimal ranges for cutting parameters. At the same time, it is appointed that abrasive flow mass is the main factor that affects surface quality, followed by the stand-off distance and the hydraulic pressure.

Similar results have been obtained by Kumaran et al. [25], who concludes that high hydraulic pressures with low transverse traverse speeds improve the surface quality. This research used an ANFIS model in the range of 220 and 260 MPa for hydraulic pressures, 20 and 40 mm/min for transverse traverse speed and 1–3 mm for stand-off distance. Also Ahmed's [26] and Jagadish's results [27] are in agreement with Kumaran, but in these cases making use of a RSM statistical model to study the influence of cutting parameters.

El-Hofy et al. [17] studied the influence of cutting parameters in two different CFRP configurations in the range of 100–350 MPa, 50–150 mm/min, and 2–4 mm for stand-off distance, concluding that hydraulic pressure is the most important factor in surface quality. Both plates are composed of an epoxy resin cured by autoclave with fibers of T800 module and a final thickness of 10.4 mm. This does not match with the results obtained by Ming [24]. El-Hofy indicated that increasing hydraulic pressure, rises the water jet kinetic energy, reducing the lag generated by the high transverse feed and so, improving the final surface quality. Nevertheless, in terms of cutting thickness, Jagadeesh et al. [28] demonstrated that the increase of thickness in CFRP machining has heavy wear effects on surface quality, while the increase in traverse speed significantly deteriorates surface quality.

On the other hand, the study of abrasive water jet machining on thermoplastic matrix composite materials—CFRTP—has not been sufficiently studied, highlighting the works developed by Pahuja et al. [14, 29] and Kakinuma et al. [30].

Pahuja et al. carried a study on the AWJM machining of a *fiber metal laminate* (FML) composed by titanium and graphite sheets bonded by a thermoplastic (PEEK) matrix. In this research, main defects were taper angle and surface quality. RSM was used to obtain a predictive mathematical model in order to predict the formation of these defects, together with a new one, so-called “hydro-distortion”, that comes given by the different machinability of the stacked materials [14, 29].

Kakinuma addresses a wider technological study, by comparing different non-conventional technologies like *ultrasonic vibration-assisted drilling* (UVD), *ultrafast feed drilling*

(UFFD), and *abrasive water jet drilling* in CFRTPs. It is composed of a PA66 nylon thermoplastic with a fiber content of 45% and a final thickness of 3 mm. In this case, it is reported that the application of high pressures may cause general damage to the surface of the CFRTP. It is also remarked that surface quality in AWJM is worse than UFFD, due to the fact that the surface is covered by the matrix, which has been melted and adhered. However, for both processes, average roughness (R_a) values are similar and close to the values required in the industry [30].

The literature about the machining of CFRPs and CFRTPs by AWJM does not show convergence in the published results. For both materials, it seems that hydraulic pressure is the main parameter, but the influence of abrasive flow mass is also considered as very relevant.

In the same way, the defects generated in the water jet machining of CFRTPs are not detailed and studied in depth in the bibliography. Pahuja and Kakinuma set new advances in water jet cutting of thermoplastic composites. Both study the surface quality obtained after machining in terms of roughness average means (R_a). Pahuja et al. [29] focus on machining hybrid structures joined by thermoplastic matrix (TiGr) and Kakinuma et al. [30] established a comparison of technologies for drilling operations in CFRTP. In this way, Kakinuma makes an approximation to the final state of the surface quality in CFRTPs after machining operations. This article concludes that the use of abrasive water jet machining in CFRTPs achieves R_a values obtained by other technologies in the industry for a thickness of 3 mm.

From the literature studied on the machining of CFRTPs, no relationship has been identified between AWJM cutting parameters and the surface quality obtained. Based on the literature on the machining of thermoset composites, hydraulic pressure and abrasive flow appear to be the most influential parameters on surface quality. However, this may differ in machining of thermoplastic composites. In addition, literature indicates that according to the combination of cutting parameters, there may be three regions of different surface quality after abrasive water jet machining. A first region affected by the erosion of abrasive particles, a second with a smooth surface and a last one with a high roughness due to the loss of cutting capacity of water jet.

This article studies the influence of cutting parameters in water jet machining of CFRTP composite materials, focusing

towards a relevant aspect that is not enough studied in the bibliography, the final surface quality.

This requirement has been evaluated in terms of R_a in three different regions of the machined surface. Mathematical models have been proposed from a response surface methodology, while the influence of parameters has been studied by an ANOVA analysis. In addition, main defects have been identified, and optimal ranges for cutting parameters are proposed.

2 Materials and methods

A TPU thermoplastic matrix CFRTP was selected for trials, with the characteristics shown in Table 1. The carbon fiber weave used is type Twill 200 g/m² with a thickness of 0.25 mm. The applied matrix is polyurethane thermoplastic with a melting temperature of 145 °C. Delamination is a critical defect in thin materials. For this reason, in this study, it has been decided to machine a 1.53-mm-thick composite in order to observe the influence of cutting parameters on thin materials.

A surface response methodology (RSM) was previously established. Several studies [24, 29, 31, 32] have used this methodology to relate the parameters studied with the input variables. A total of 20 trials have been obtained by combining the three levels per variable according to the established methodology (Table 2).

These parameters have been designated based on the limitations of the equipment used as well as the levels most employed in the literature reviewed [16, 17, 21, 24, 27, 28].

The objective of using an RSM is to establish an empirical model that establishes multiple linear regression. An ANOVA analysis has been performed using this methodology to subsequently obtain a series of contour diagrams or response surfaces. A second-order polynomial is used to obtain these response surfaces (Eq. 1). This kind of mathematical model is widely used in research on non-conventional machining processes in order to relate the defects studied with the selected cutting parameters [31–34].

$$Y = C_0 + \sum_{i=1}^k C_i x_i + \sum_{i=1}^k C_{ii} x_i^2 + \sum_{i < j}^k C_{ij} x_i x_j + \epsilon \quad (1)$$

t1.1 **Table 1** CFRTP characteristics

t1.2	Ply orientation	Number of plies	Thickness	Thermoplastic	Fiber/matrix (%)
t1.3	[0°/90°] _s	7	1.53 mm	TPU (polyurethane)	74.20 / 25.80
t1.4		Tensile strength (MPa)	Young modulus (GPa)	ILSS (MPa)	
t1.5		567.36	45.98	199.10	

t2.1 **Table 2** Cutting parameters set

t2.2 Parameter	Level 1	Level 0	Level 1
t2.3 Hydraulic pressure-P (MPa)	120	250	340
t2.4 Traverse speed-v (mm/min)	100	300	500
t2.5 Abrasive mass flow-m a (g/min)	170	225	340

237 Y corresponds to the expected response, in this case the
 238 mean surface roughness (R_a), x_i are the parameters used in
 239 the study, C_0, C_i, C_{ii}, C_{ij} , the regression coefficients, and ϵ
 240 the random error of the model.

241 A water jet machine (TCI Cutting, BP-C 3020, Valencia,
 242 Spain) has been used with a nozzle diameter of 0.8 mm, an
 243 orifice diameter of 0.3 mm, and a nozzle length of 94.7 mm.
 244 The AWJM machine is equipped with an ultra-high capacity
 245 pump (KMT, 158 Streamline PRO-2 60, Bad Nauheim,
 246 Germany).

247 Slots with lengths of 15 mm were machined for each com-
 248 bination of cutting parameters (Fig. 1). Machining starts
 249 10 mm before the material to achieve a constant flow of water
 250 and abrasive.

251 A 120 mesh Indian garnet abrasive size has been used
 252 during machining to improve the cutting capacity of the water
 253 jet. Figure 2 shows the main chemical composition of the
 254 abrasive particles used during machining.

255 After machining, the surface quality was evaluated
 256 through the arithmetic mean roughness parameter (R_a).
 257 Although there are more parameters to evaluate the surface
 258 quality obtained, the R_a parameter has been widely used in
 259 diverse bibliography [16, 24, 35–37] allowing, thus, a
 260 comparison of results for the machining of different mate-
 261 rials and cutting conditions. A roughness meter was used
 262 (Mahr Perthometer PGK 120, Göttingen, Germany), fol-
 263 lowing *ISO 4288:1999* standard. Literature indicates the
 264 existence up to three zones of different surface quality in
 265 abrasive water jet machining [16, 38]. These zones present
 266 a high initial roughness due to the erosive effect, a soft
 267 zone where the water jet stabilizes and a zone of poorer
 268 surface quality due to the loss of kinetic energy. In addi-
 269 tion, due to the low thickness of the material, areas with
 270 groove or lag defects are not appreciated. Due to this,
 271 parameters such as W_t (maximum height of waviness) used
 272 to evaluate the waviness in this type of defect have not
 273 been applied [39].

274 In accordance with the literature [16, 24, 40], three regions
 275 of different surface quality are appreciated after machining.
 276 Due to the low thickness of the composite, an auxiliary tool
 277 has been manufactured to ensure the placement of material on
 278 the roughness meter.

279 R_a was evaluated at three points equidistant at 0.4 mm
 280 (Fig. 3) by using a goniometer placed on the evaluation
 281 table of the roughness meter, referred to as *Entry, Central,*

and *Outflow*. Measurements were made at 0.35 mm from 282
 the edges. A cut-off of 2.5 mm was established for a total 283
 evaluation length of 12.25 mm. Stylus with 2 μ m tip radius 284
 and 90° tip angle was used for the measurements. Finally, 285
 scanning electron microscopy (Hitachi, VP-SEM SU1510, 286
 Schaumburg, EEUU) techniques were used in order to char- 287
 acterize the defects produced during the process. 288

3 Results 289

3.1 SEM defect identification 290

As indicated in the literature, the formation of an EAZ at the jet 291
 entry is an inherent defect of this process. This is appreciated in 292
 Fig. 4, where the change in surface quality is appreciated 293
 visually. 294

Remains of abrasive particles after the impact of the water 295
 jet at the entry of the material appear to be adhered to the 296
 surface generated after the cutting [21]. They may have ad- 297
 hered to the surface because of the loss of kinetic energy 298
 during the process. These particles can generate a rougher 299
 zone by increasing the values of R_a at the input. 300

Two defects in the machining of CFRTPs by AWJM are 301
 seen in Fig. 5. On the one hand, there is an area where carbon 302
 fibers are visible without matrix in form of delamination. This 303
 is due to the erosive effect of the water jet that has eliminated 304
 the matrix. This is consistent with the results obtained in [21]. 305

On the other hand, the thermoplastic matrix does not seem 306
 to detach in the outflow area of the water jet, remaining ad- 307
 hered to the generated surface. This defect is known as burr in 308
 the studies performed in [4, 13], due to the fact that the ther- 309
 moplastic matrix is removed by the temperatures achieved in 310
 conventional processes, leaving the carbon fibers without re- 311
 inforcement. However, in machining by water jet cutting, the 312
 defect generated is the opposite, being the carbon fibers re- 313
 moved in the correct way while the thermoplastic matrix does 314
 not detach from the surface giving rise to a fraying defect. 315

These defects at the outflow may alter the values of R_a , 316
 which could result in higher values at the outflow than in the 317
 intermediate or entry zones, as in test 9 corresponding to a 318
 pressure of 250 MPa, a mass flow of 225 g/min and a traverse 319
 speed of 300 mm/min. 320

The main defect in the machining of composites by water 321
 jet machining is delamination [21]. Delaminations are 322

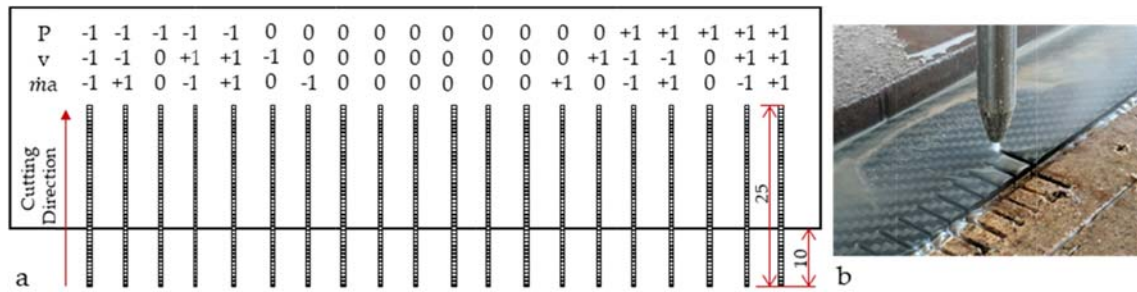


Fig. 1 a Graphic representation of the experimental design. b Trials carried out

323 considered as the collapse or rupture in the area of union of the
 324 layers that compose the composite material due to the forma-
 325 tion of a crack perpendicular to the cut [23].

326 When the water jet hits the material, the thickness of the
 327 unmachined material is constantly reduced. This produces a
 328 decrease in its resistance to deformation that may result in the
 329 adhesion between layers not supporting the stresses generated
 330 producing the delamination defect [21].

331 At the same time, when the initial separation of the layers is
 332 generated and the material is not completely mechanized, the
 333 flow of water penetrates through the small cavities generated.

334 This produces, on the one hand, an increase in the maxi-
 335 mum length of the delaminations produced and, on the other,
 336 the possibility of penetration and incrustation of abrasive parti-
 337 cles in the generated cavities [41], increasing the size of the
 338 delamination produced (Fig. 6).

339 This defect has been only generated for the combination of
 340 a pressure of 120 MPa with a mass flow of 340 g/min and a
 341 traverse speed of 100 mm/min. This is usually also in the

342 machining of thermoset matrix composites and has been re-
 343 ported previously in [21, 28, 42].

344 Abrasive particles are introduced in the cavities increasing
 345 the separation between the layers that compose the CFRTP.
 346 The combination of a very low *traverse speed* with a very high
 347 *mass flow* eases the elimination of the thermoplastic matrix.
 348 This allows the abrasive particles to remove the carbon fibers
 349 and produce delamination.

3.2 Influence of cutting parameters on surface quality 350

351 The values of R_a obtained in the three regions (Entry, Central,
 352 and Outflow), as well as their arithmetic mean roughness and
 353 standard deviation (average R_a), are indicated in Table 3.

354 In most tests, the highest values of R_a are observed in the
 355 area corresponding to the inlet of the water jet. The first con-
 356 tact of the abrasive particles with the material produces an area
 357 very affected by erosion until the jet is able to penetrate the
 358 thickness of the material. Nevertheless, in two tests, the values

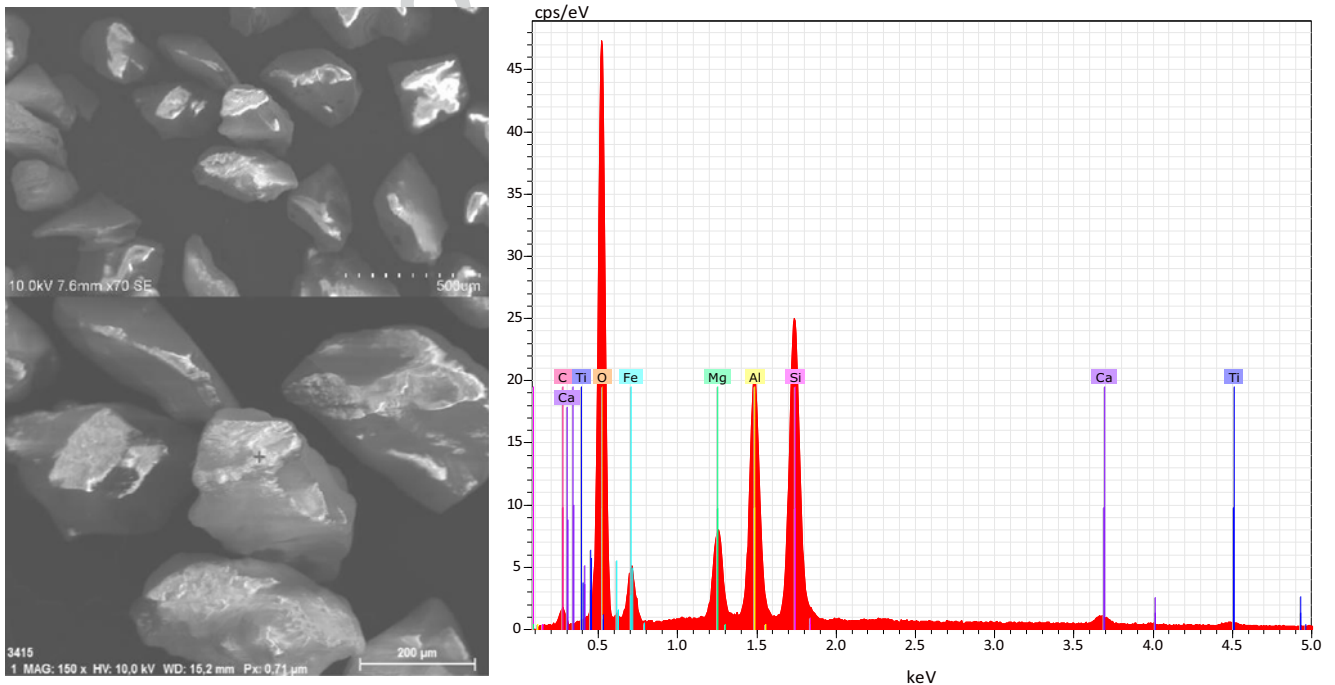


Fig. 2 SEM images at 70× and 150× of the abrasive particles used and chemical composition by EDS analysis

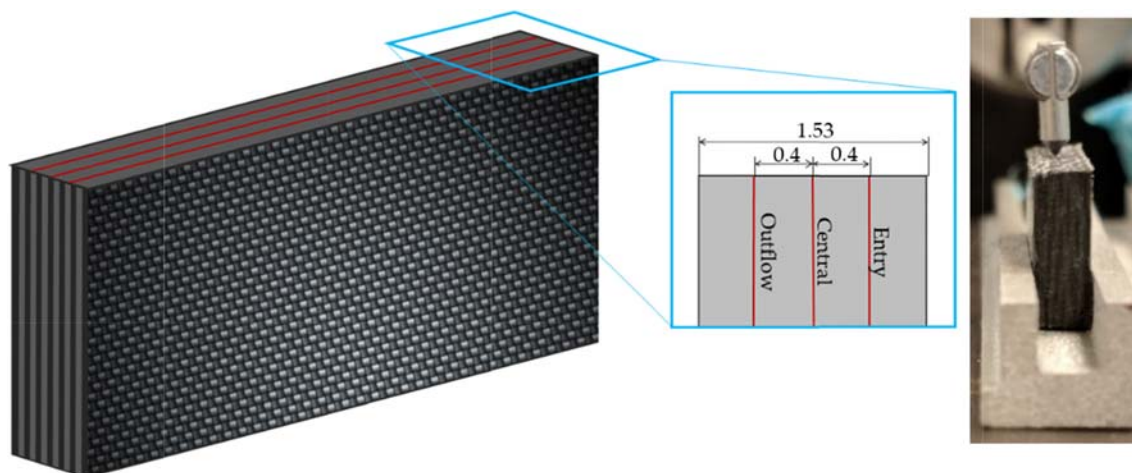


Fig. 3 Surface quality methodology

359 of R_a at the output are higher than the values at the entry side.
 360 Due to the low viscosity of the thermoplastic polymer [43], the
 361 integration between matrix and reinforcement (carbon fibers)
 362 can be overcome by the shear stresses generated by the water
 363 jet when machining the material. This produces that the thermoplastic
 364 matrix is not completely eliminated, and may remain adhered to the surface [30] or not detach completely at the end of the cut, causing a fraying defect.

367 When the roughness meter evaluates the outflow region,
 368 the detachment of the thermoplastic matrix in the form of
 369 fraying can alter the measurement collected, obtaining these
 370 higher R_a values. Therefore, there are no statistically significant
 371 differences between the values obtained.

372 Average values of R_a between 4.77 and 6.95 μm have been
 373 obtained. In comparison with the literature studied on abrasive
 374 water jet machining of thermoset composite materials, close
 375 values have been obtained despite the use of a low melting
 376 point thermoplastic matrix [24, 37, 44, 45].

377 On the contrary, in comparison with the results obtained by
 378 Kakinuma in CFRTP (2.5 μm), higher values have been obtained
 379 possibly due to the use of a different thermoplastic.
 380 Kakinuma uses a modified polyamide 66 thermoplastic resin
 381 (Nylon66) that can reach a melting temperature of 260 $^{\circ}\text{C}$. In
 382 comparison, the polyurethane applied in this article has a

melting temperature of 145 $^{\circ}\text{C}$. This can lead to the loss of
 thermoplastic matrix and result in poorer surface quality.

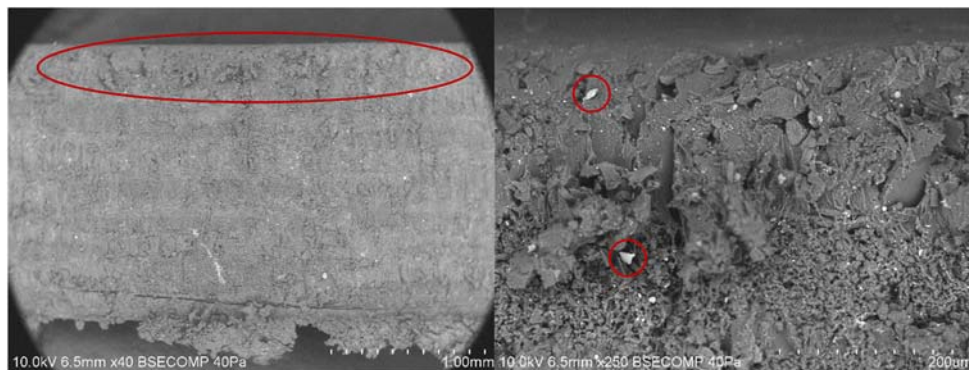
A complementary experimental design has been carried out, in order to validate the results obtained through the response surface methodology. Combinations of cutting parameters not included in the original DOE have been made. The values of R_a obtained have been compared with those predicted by the original model for these same combinations of parameters (Table 4).

The literature researched indicates the formation of three regions of different surface quality after abrasive water jet machining in any kind of material. The creation of these regions is related to the selection of cutting parameters [16, 32].

In the results obtained in this study, there is not a great difference between the three regions evaluated, being the highest values of R_a in the entry zone due to the erosion of abrasive particles at the entry of the water jet. In the same way, in comparison with the results obtained in [16, 24], the formation of a third rougher zone is not observed. This could be due to the properties of the thermoplastic matrix and the low thickness of the material.

The third region is usually associated with a very high loss of kinetic energy from the water jet when the thickness is very high. This loss of kinetic energy reduces the cutting capacity

Fig. 4 Erosion zone due to the action of abrasive particles at the entrance of the water jet at 40 \times and 250 \times



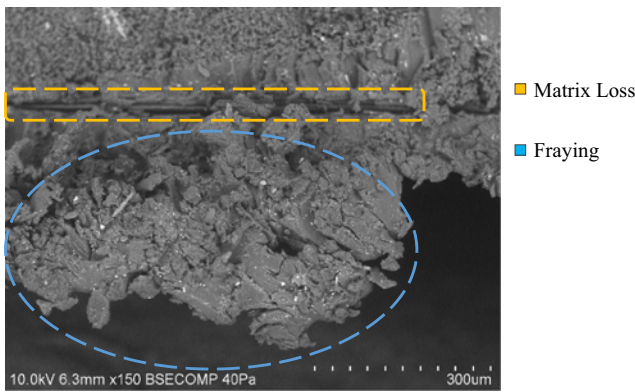


Fig. 5 Burr generated in the output of the water jet and loss of matrix at 150×

407 of the process, generating defects such as grooves and a worse
 408 final surface quality. However, when machining such a small
 409 thickness, the loss of kinetic energy suffered by the water jet is
 410 not significant. Very homogeneous surfaces are obtained by
 411 machining CFRTPs for small thicknesses.

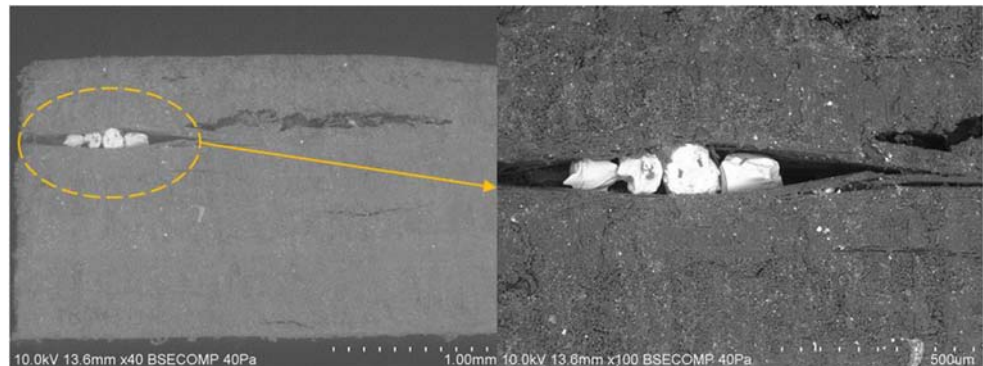
412 **3.2.1 Effect of hydraulic pressure on surface quality**

413 The effect of the variation in *hydraulic pressure* on the surface
 414 quality is shown in Fig. 7. An increase in kinetic energy is
 415 obtained by increasing the *pressure*, obtaining R_a values that
 416 are lower and close to each other, mainly in the intermediate
 417 and exit zones. R_a values decrease and a more homogeneous
 418 surface is obtained. An increase in *pressure* gives greater ki-
 419 netic energy to the particles by increasing their cutting capac-
 420 ity [16, 21]. However, an increase in *pressure* produces a
 421 greater erosive effect at the inlet leading to higher values at
 422 the entry of the jet (Fig. 4).

423 **3.2.2 Effect of traverse speed on surface quality**

424 In agreement with [14, 17, 21], higher R_a values are obtained
 425 at the water-jet entry (Fig. 8). Discarding this zone, influence
 426 of the *traverse speed* on the R_a values is not appreciated. An
 427 increase of this parameter generates values of R_a closer in the

Fig. 6 Abrasive particles between the layers of the CFRTP, producing delamination at 40× and 100×



three evaluated zones, generating a more homogeneous surface. 428
 429

Of the results obtained, the most homogeneous surface 430
 after machining is obtained at a *traverse speed* of 300 mm/ 431
 min. However, an increase in this value combined with the 432
 erosive effect of the jet would result in a greater dispersion, 433
 producing a worse surface quality. If the *traverse speed* is not 434
 adequate, the abrasive effect at the entry of the jet seems to 435
 increase. The use of *traverse speeds* of 100 mm/min offers the 436
 lowest R_a values in almost all thickness. Nonetheless, the area 437
 affected by erosion is more pronounced. This may be due to 438
 an excess of abrasive particles affecting the entrance of the 439
 material for a very long time producing an increase in the 440
 roughness generated in this area (Fig. 3). On the contrary, an 441
 excess of *traverse speed* could indicate that the whole thick- 442
 ness is not machined in a homogeneous way, generating vari- 443
 ations between the entry and exit of the jet [24]. 444

However, within the range of selected cutting parameters, 445
 there is no influence on the arithmetic mean roughness obtain- 446
 ed in the thickness. Very close values of mean R_a are obtained 447
 for the three case studies. It could be said that the variation in 448
traverse speed seems to affect only the surface quality corre- 449
 sponding to the entry of the water jet into the material. 450

451 **3.2.3 Effect of abrasive flow rate on surface quality**

The influence of the *ma* on the surface quality is plotted in 452
 Fig. 9. An increase of the average R_a is obtained by increasing 453
 the *abrasive flow* from 170 to 340 g/min, due to a greater 454
 number of abrasive particles impacting on the material, 455
 reaching a greater cutting capacity. 456

This is consistent with the results obtained by the ANOVA 457
 analysis. It indicates that *abrasive mass flow* is the parameter 458
 with the highest statistical significance in surface quality. 459

It is noticeable that while R_a increases, dispersion de- 460
 creases. A loss of kinetic energy in abrasive particles can 461
 occur if the *ma* is increased excessively, where inter- 462
 particulate collisions would produce also a worse surface fin- 463
 ish [46]. An *ma* of 170 g/min seems to generate the lowest 464
 mean value of R_a . Also, the dispersion generated over the full 465

t3.1 **Table 3** Ra values obtained in all
t3.2 tests

Test	Pressure [MPa]	Traverse speed [mm/min]	Abrasive [g/min]	Entry R_a [μm]	Central R_a [μm]	Outflow R_a [μm]	Average R_a [$\mu\text{m} \pm (\mu\text{m})$]
t3.3	1	120	100	170	6.45	5.87	5.87 \pm 0.48
t3.4	2	120	100	340	7.45	6.83	6.95 \pm 0.37
t3.5	3	120	300	225	6.99	6.61	6.47 \pm 0.49
t3.6	4	120	500	170	6.13	5.00	5.29 \pm 0.60
t3.7	5	120	500	340	6.74	6.88	6.73 \pm 0.13
t3.8	6	250	100	225	6.76	4.88	5.73 \pm 0.78
t3.9	7	250	300	170	6.14	5.39	5.33 \pm 0.69
t3.10	8	250	300	225	5.87	5.85	5.69 \pm 0.24
t3.11	9	250	300	225	5.09	5.59	5.66 \pm 0.27
t3.12	10	250	300	225	5.39	5.01	5.29 \pm 0.23
t3.13	11	250	300	225	5.34	5.31	5.21 \pm 0.11
t3.14	12	250	300	225	5.80	6.46	5.90 \pm 0.46
t3.15	13	250	300	225	5.31	5.59	5.44 \pm 0.14
t3.16	14	250	300	340	6.00	5.94	5.90 \pm 0.10
t3.17	15	250	500	225	6.63	5.18	5.67 \pm 0.68
t3.18	16	340	100	170	4.88	4.74	4.77 \pm 0.08
t3.19	17	340	100	340	6.73	5.53	5.90 \pm 0.59
t3.20	18	340	300	225	6.87	5.51	5.89 \pm 0.70
t3.21	19	340	500	170	6.44	5.69	5.63 \pm 0.69
t3.22	20	340	500	340	6.73	5.12	5.66 \pm 0.76

466 thickness increases, due to the fact that the amount of particles
467 used for cutting is insufficient to generate a smooth cut at the
468 entry of the material.

469 **3.2.4 Effect of the interaction of cutting parameters**
470 **on surface quality**

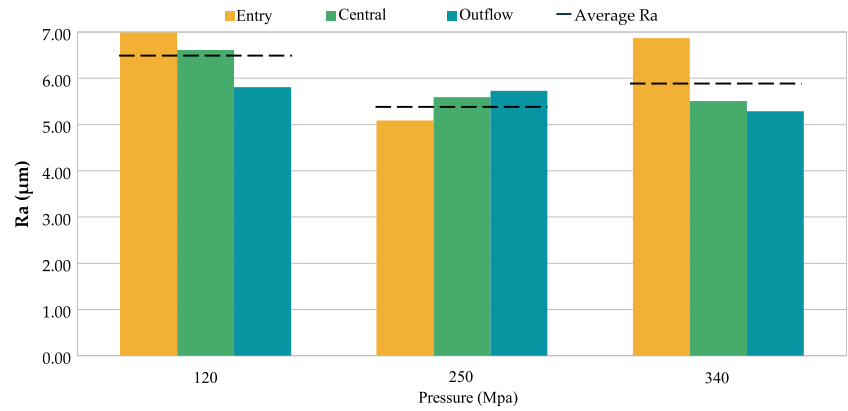
471 The interaction of the cutting parameters and their influence
472 on the surface quality in terms of mean values of R_a is shown

in Fig. 10. In this graph, it can be seen again that the *traverse* 473
speed does not produce a considerable variation in surface 474
quality in combination with *hydraulic pressure* and *abrasive* 475
flow. Thus, for example, it can be seen that, although the 476
traverse speed increases from 100 to 500 mm/min for an 477
abrasive flow of 170 g/min, the values of R_a are very close 478
to 5 μm . On the contrary, as mentioned in the previous sec- 479
tions, an increase in the *abrasive flow* if it generates a consid- 480
erable increase in surface quality. Thus, there is an increase in 481

t4.1 **Table 4** Complementary DOE
t4.2 for validation of the mathematical
model

Test	Pressure [MPa]	Traverse speed [mm/min]	Abrasive [g/min]	Average R_a [$\mu\text{m} \pm (\mu\text{m})$]	Average predicted R_a [μm]	
t4.3	1	120	300	170	6.13 \pm 0.63	5.68
t4.4	2	120	100	225	6.51 \pm 0.13	6.56
t4.5	3	120	500	225	5.58 \pm 0.32	6.15
t4.6	4	120	300	340	7.72 \pm 0.78	6.87
t4.7	5	250	100	170	5.28 \pm 0.34	4.95
t4.8	6	250	500	170	5.08 \pm 0.64	5.09
t4.9	7	250	100	340	6.71 \pm 0.36	5.99
t4.10	8	250	500	340	5.33 \pm 0.53	5.75
t4.11	9	340	300	170	4.71 \pm 0.55	5.32
t4.12	10	340	100	225	5.38 \pm 0.51	5.51
t4.13	11	340	500	225	5.71 \pm 0.45	5.81
t4.14	12	340	300	340	5.20 \pm 0.24	5.83

Fig. 7 Variation of R_a in the three zones as a function of pressure ($\dot{m} = 225$ g/min; $v = 300$ mm/min)



482 the value of R_a from 5 μm to more than 7 μm , due to the loss
 483 of cutting capacity of the particles due to their intercollision.

484 On the contrary, the interaction between the *hydraulic*
 485 *pressure* and the *traverse speed* does show interesting results.
 486 Although, according to the ANOVA analysis obtained, they
 487 do not have a significant influence on the results obtained, Fig.
 488 10 shows how, for a given value of *hydraulic pressure*, the
 489 increase in abrasive particles in the flow worsens the surface
 490 quality.

491 While for *abrasive flows* of 225 g/min and 340 g/min, the
 492 R_a values are reduced by increasing *hydraulic pressure* due to
 493 the increased kinetic energy of the water jet, for values of
 494 170 g/min, a high *pressure* produces a turning point. This
 495 may be due to the fact that, although the kinetic energy of
 496 the water particles increases as does their cutting capacity,
 497 the amount of abrasive particles required to machine the layers
 498 of the composite material is insufficient, thus producing a
 499 rougher surface. In addition, if the number of particles is in-
 500 sufficient, the remains of the thermoplastic matrix generated
 501 during cutting may not be eliminated, remaining adhered to
 502 the surface and producing an increase in the values of R_a [30].

503 **3.3 Statistical analysis**

504 An ANOVA analysis of the obtained R_a values is shown in
 505 Table 5. In parallel, second-order quadratic models are usually

506 used because they have a high reliability when relating the
 507 variables used with the results obtained [28, 32, 47]. The
 508 second-order quadratic model applied has a p value less than
 509 0.05, indicating that it is statistically significant.

510 The *hydraulic pressure* and the \dot{m} are the variables that
 511 directly influence the R_a values. On the contrary, the *traverse*
 512 *speed* has p values greater than 0.05, which would indicate
 513 that it is an excluding variable. The significance of each pa-
 514 rameter is determined by the value F. Higher values of F indi-
 515 cate a high influence on the response. Observing the analysis
 516 carried out, it can be indicated that the main parameter affect-
 517 ing surface quality is the \dot{m} , followed by *hydraulic pressure*.
 518 This is consistent with the results of the literature consulted.

519 The mathematical model obtained through the response
 520 surface methodology is shown in Eq. 2. It presents an R^2 of
 521 83%, which indicates a good fit with the experimental results.
 522

$$\begin{aligned}
 Ra = & 5.6144 - 0.3463P - 0.0250v + 0.4260\dot{m} \\
 & + 0.438P^2 - 0.042v^2 - 0.127 \\
 & + 0.176P*v - 0.170P*\dot{m} - 0.094v*\dot{m}
 \end{aligned} \tag{2}$$

Fig. 8 Variation of R_a in the three zones evaluated as a function of traverse speed ($P = 2500$ bar; $\dot{m} = 225$ g/min)

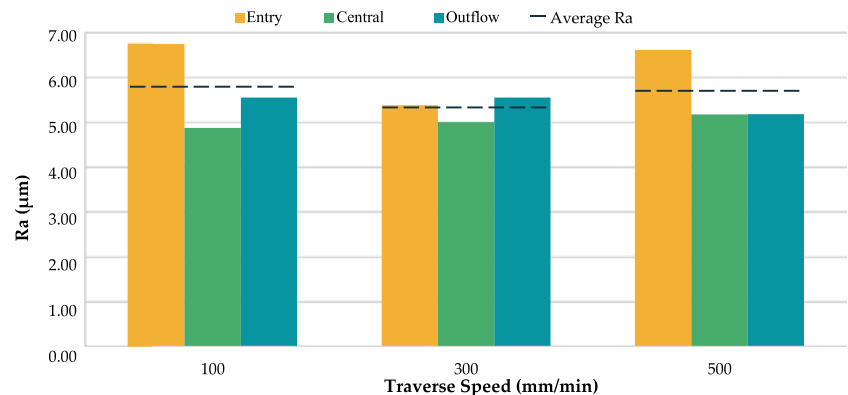
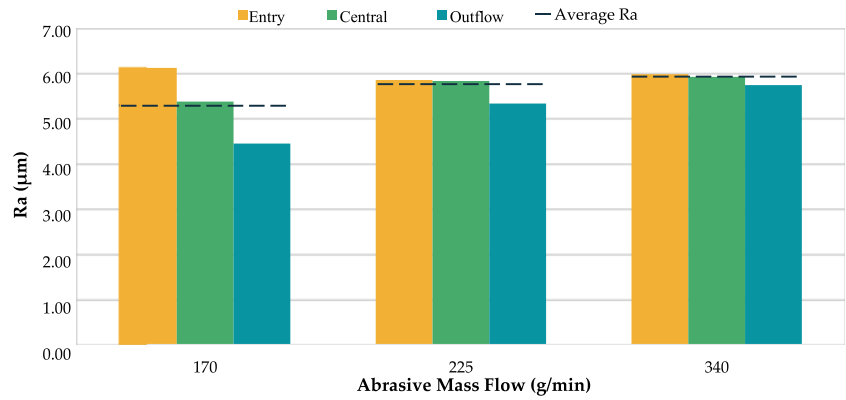


Fig. 9 Variation of R_a in the three zones evaluated according to the established \dot{m}_a ($P = 2500$ bar; $v = 300$ mm/min)



526 **3.4 Response surface**

527 Contour surfaces have been obtained using a RSM, plotting
 528 the interaction of two input parameters in the output variable,
 529 by keeping as constant the rest of parameters.

530 The selected parameters have been the hydraulic pressure and the
 531 \dot{m}_a , as they are the most significant parameters according to the ANOVA analysis.
 532

533 As is seen in Fig. 11, the most influential parameter on surface quality is the
 534 *abrasive mass flow*. A value close to 170 g/min combined with *hydraulic pressures* between 120
 535 and 340 MPa offers the lowest R_a values.
 536

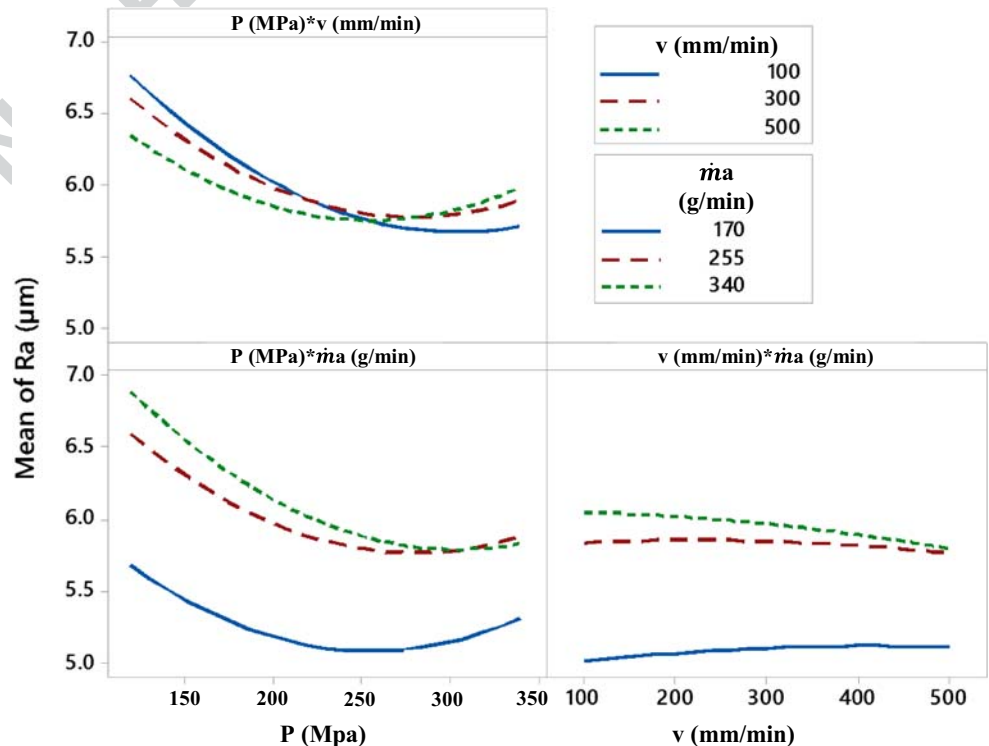
537 On the other hand, a combination of a *pressure* of 120 MPa and a *mass flow* of 340 g/min considerably increases the R_a
 538

539 values resulting in poorer surface quality. This is due to the
 540 low kinetic energy given to abrasive particles reducing their
 541 cutting capacity.

542 Different surface qualities are appreciated in Fig. 10a,
 543 which corresponds to the worst surface quality ($P =$
 544 120 MPa; $\dot{m}_a = 340$ g/min), and Fig. 10b, related to the best
 545 surface quality ($P = 250$ MPa; $\dot{m}_a = 170$ g/min).
 546

547 A more homogeneous surface is obtained for the optimal
 548 combination of cutting parameters, according to the mathe-
 549 matical model obtained (Fig. 12a). The EAZ appears to be
 550 smaller and no burrs are produced at the outflow of the water
 551 jet. This can be seen in the surface quality appreciated in the
 552 first section of the thickness corresponding to the initial zone
 553 of entry of the water jet. In this zone, the erosion generated at

Fig. 10 Effect of the interaction of input variables on the surface quality obtained in terms of R_a



t5.1 **Table 5** ANOVA analysis of the R_a values obtained

t5.2 Source	DF	Adj SS	Adj MS	F value	P value
t5.3 Model	9	4.21331	0.46815	5.74	0.006
t5.4 P (MPa)	1	1.27804	1.27804	15.68	0.003
t5.5 v (mm/min)	1	0.014	0.014	0.17	0.687
t5.6 $\dot{m} a$ (g/min)	1	1.86589	1.86589	22.89	0.001
t5.7 P (MPa)* P (MPa)	1	0.39246	0.39246	4.81	0.053
t5.8 v (mm/min)* v (mm/min)	1	0.00592	0.00592	0.07	0.793
t5.9 $\dot{m} a$ (g/min)* $\dot{m} a$ (g/min)	1	0.19789	0.19789	2.43	0.15
t5.10 P (MPa)* v (mm/min)	1	0.24261	0.24261	2.98	0.115
t5.11 P (MPa)* $\dot{m} a$ (g/min)	1	0.24819	0.24819	3.04	0.112
t5.12 v (mm/min)* $\dot{m} a$ (g/min)	1	0.06432	0.06432	0.79	0.395
t5.13 Error	10	0.81522	0.08152		
t5.14 Lack-of-fit	5	0.46115	0.09223	1.3	0.389
t5.15 Pure error	5	0.35407	0.07081		
t5.16 Total	19	5.02854			

553 the beginning by the abrasive particles seems to be less visi-
 554 ble, offering a more homogeneous surface in the whole
 555 thickness.

556 On the other hand, in Fig. 12b, the difference in surface
 557 quality is visually appreciated in this area in comparison with
 558 the rest of the thickness. This would indicate that the EAZ is
 559 larger for this combination of cutting parameters. In addition,
 560 the increase in *hydraulic pressure* gives a greater cutting
 561 capacity to the water jet, being able to completely eliminate the
 562 thermoplastic matrix at the exit of the material eliminating the
 563 defect of fraying at the exit.

564 However, in both of cases, the loss of the matrix by the
 565 erosive effect of the jet is appreciated, producing cracks with
 566 visible carbon fibers.

567 Figure 13 shows a graphical representation of the optimi-
 568 zation of surface quality (R_a) according to the mathematical
 569 model obtained. A combination of v of 100 mm/min, an $\dot{m} a$ of
 570 170 g/min and a P of 280 MPa should give the lower R_a , of

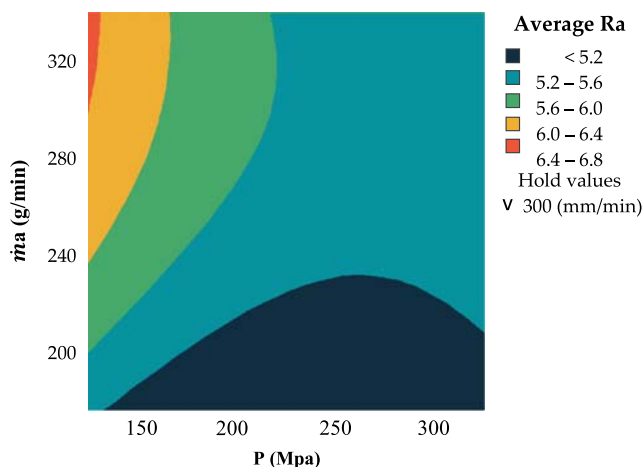


Fig. 11 Contour plot of R_a as a function of P and $\dot{m} a$

571 about 4.92 μm . The figure also indicates the degree of desir-
 572 ability of the result obtained. Individual and composite desir-
 573 ability assess how well a combination of variables satisfies the
 574 goals you have defined for the responses.

575 Individual desirability (d) evaluates how the settings opti-
 576 mize a single response; composite desirability (D) evaluates
 577 how the settings optimize a set of responses overall. Desirability
 578 has a range of zero to one. One represents the ideal case; zero
 579 indicates that one or more responses are outside their accept-
 580 able limits. In the result obtained, the desirability obtained is
 581 0.93 which would indicate that the combination of cutting
 582 parameters indicated offers a result according to the desired.
 583

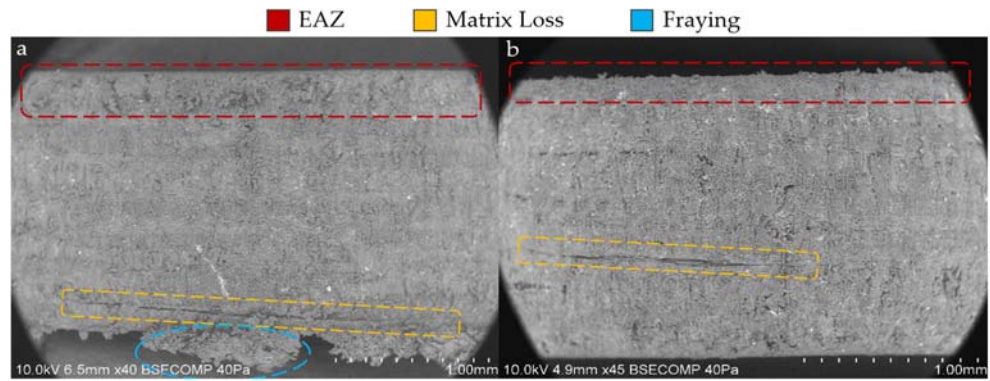
3.5 Mathematical model validation

584 Figure 14 represents a comparison between the experimental
 585 and the predicted values, showing very close results, with a
 586 maximum error of 7.87%. This fact indicates the high reliabil-
 587 ity of the process.

588 In order to validate the mathematical model, a comparison
 589 between combinations of not used parameters in the original
 590 DOE and the predicted values has been carried out in the same
 591 way (Fig. 15).

592 Although there are major differences, the maximum error
 593 obtained was 13.07%. A very good fit has been obtained for
 594 the mathematical model used. It is worth noting the disparity
 595 of results obtained in the literature about CFRTP machining.
 596 In addition, this error can be caused by the anisotropy of this
 597 type of materials and defects such as fraying that may alter the
 598 surface quality values. This model could be used to predict
 599 and improve the surface quality in the abrasive water-jet ma-
 600 chining of CFRTPs.
 601

Fig. 12 Surface quality comparison obtained for a worst combination at 40×. b Optimum combination at 45×



602 **4 Discussion**

603 As indicated in the results obtained in [16, 29, 48], the results
 604 show the formation of a first zone with greater roughness. This
 605 is due to the erosion generated by the abrasive particles in the
 606 first moments of machining, which generates a zone with an
 607 affected area, a rounding at the entrance and the adhesion of
 608 abrasive particles as shown in Fig. 4 producing a worse surface
 609 quality in terms of R_a .

610 The use of a thermoplastic matrix compared to thermosets
 611 results in a number of defects. On the one hand, as in CFRP
 612 machining [23, 45], defects such as fiber pull out are produced
 613 due to the shear stresses of abrasive particles and water. This,
 614 in combination with the low viscosity of thermoplastic matrices,
 615 increases the detachment of the matrix from the reinforcement
 616 or carbon fibers. This results in visual defects where the
 617 reinforcement is free or visible. Nevertheless, unlike CFRP,
 618 the matrix is not completely eliminated at the water jet exit,
 619 generating a final fraying in the form of a cosmetic defect as
 620 shown in Fig. 5, being a characteristic defect of CFRTP
 621 machining [30, 49].

622 The combination of a reduced pressure of 120 Mpa and a
 623 high flow rate of 340 g/min does not allow the water jet to
 624 machine the material homogeneously. This reduces its cutting
 625 capacity due to the low kinetic energy of the water jet and the
 626 intercollisions of the abrasive particles as explained in [23,
 627 46]. Due to this, the water jet eliminates part of the matrix,

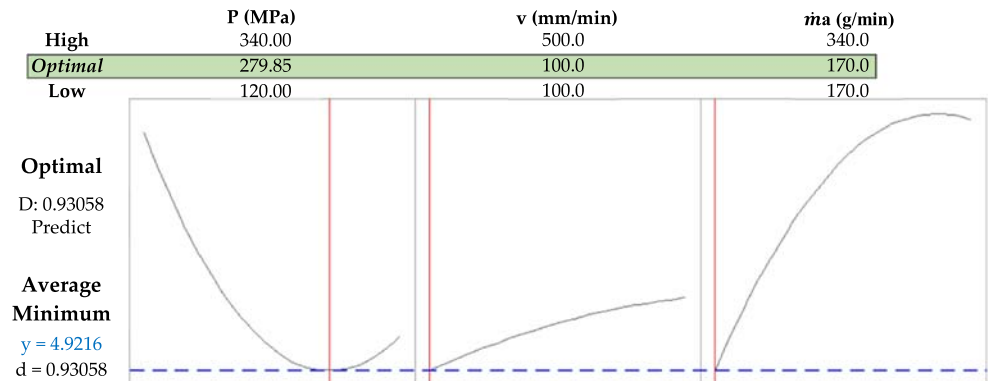
628 generating internal cavities that allow the abrasive particles to
 629 be deposited in these cavities, giving rise to the formation of
 630 delaminations in the interlayer (Fig. 6).

631 Although the literature indicates the formation of three regions
 632 of different surface quality due to the dispersion and
 633 reduction of the kinetic energy of the water jet [24, 40], the
 634 results obtained only show the formation of two regions. The
 635 first one has a higher roughness due to the erosive effect of the
 636 abrasive particles and a second smooth region, with close R_a
 637 values between the central and outflow regions. This may be
 638 due to the fact that, compared to most literature [28], the
 639 thickness of the machined material is very small, less than
 640 2 mm. This avoids the dispersion of the water jet itself, generating
 641 a homogeneous and smooth cut throughout the thickness,
 642 without forming defects such as lag and an increase in the
 643 R_a values at the water jet outlet.

644 In the indicated literature, it is explained that pressure is the
 645 most significant parameter in the surface quality obtained [17,
 646 25, 27]. The increase in hydraulic pressure is directly related
 647 to the increase in the kinetic energy of the jet particles and
 648 their cutting capacity. This allows a lower dispersion when the
 649 jet cuts the material, allowing the cutting capacity to be constant
 650 throughout the thickness and generating a homogeneous surface
 651 in terms of R_a as seen in Fig. 7.

652 On the other hand, the *traverse speed* has a fundamental
 653 role in combination with the erosion of the abrasive particles
 654 at the entry of the water jet [16, 28]. If the *traverse speed*

Fig. 13 Cutting parameter combination that minimizes R_a



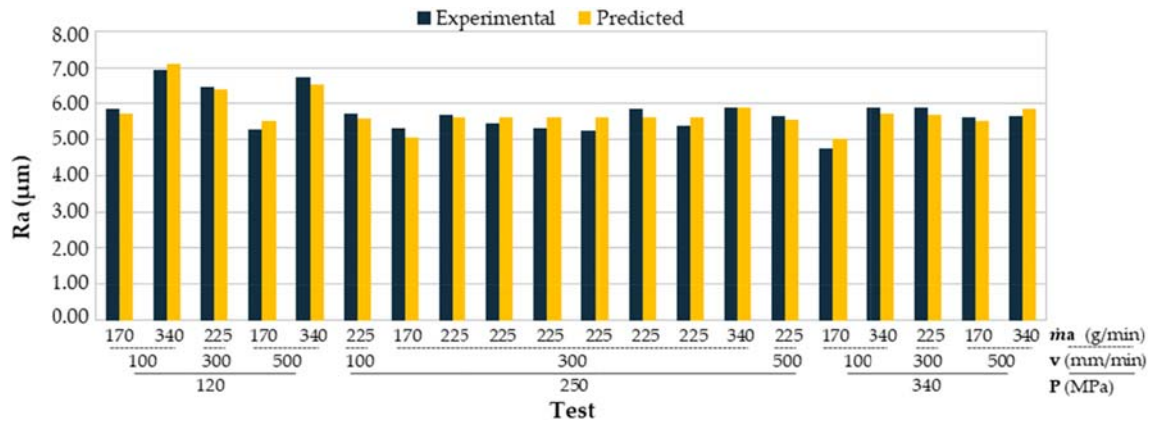


Fig. 14 R_a values (experimental and predicted)

655 increases to 300 mm/min, there is a dispersion between the
 656 amount of particles that are machining the upper part of the
 657 material compared to the lower part of the material (Figs. 8
 658 and 9). This produces a difference in cutting capacity along
 659 the thickness that produces a rougher area. Nevertheless, due
 660 to this increase in speed, the amount of abrasive particles that
 661 erode the entry zone of the water jet in a time interval is
 662 reduced, producing a less rough initial zone with R_a values
 663 in the three closest levels.

5 Conclusions

665 An experimental study on the influence of cutting parameters
 666 in surface quality, focused in the water jet machining of thermoplastic
 667 matrix reinforced with carbon fiber composite materials, has been carried out.

669 An experimental design based on a response surface methodology
 670 has been developed, obtaining a quadratic mathematical model that relates
 671 the input variables with the surface quality, in terms of average roughness,
 672 R_a .

673 The model obtained by a second external experimental design has been
 674 corroborated in order to compare the predicted values with the experimental
 675 data. An error of 13% has been obtained, which can be considered small
 676 due to the nature of the material and the randomness of the results
 677 obtained in the literature.

679 The cutting parameters used have been close to those used in the literature
 680 reviewed. In both thermoset and thermoplastic composite materials,
 681 hydraulic pressure and abrasive mass flow have a high influence on surface
 682 quality. In addition, it appears from the results obtained that the
 683 *traverse speed* used does not affect the surface quality.

685 On the other hand, the main defects caused by AWJM in thermoplastic
 686 composites are mainly delamination at the interface, burr-shaped matrix
 687 detachments in the form of fraying at the exit and a constant area of
 688 erosion caused by the erosive effect of the abrasive particles of the water
 689 jet in the first moments of the cut.

691 The surface quality of thermoplastic matrix composite materials (TPU)
 692 in three different thickness zones has been studied according to the
 693 cutting parameters established. It has been observed that the zone with
 694 the worst surface quality is the

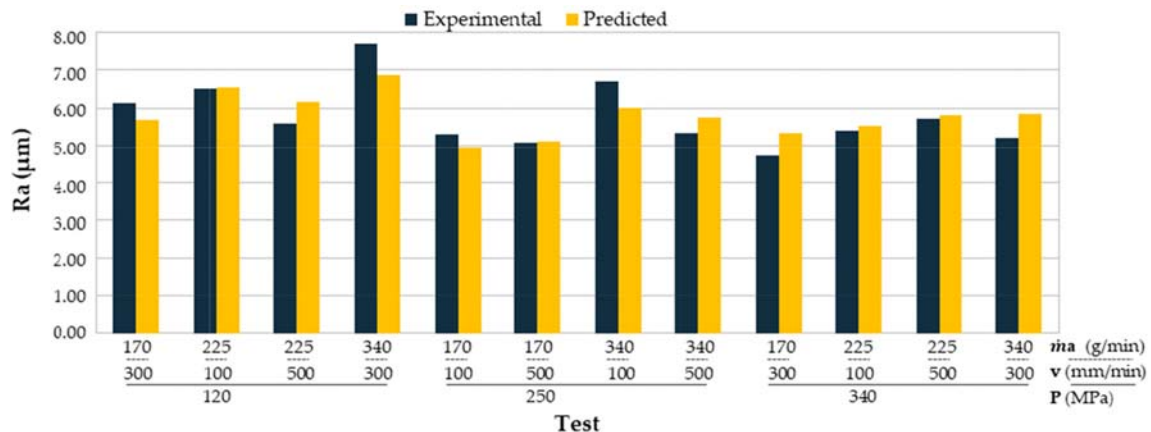


Fig. 15 R_a values in the second tests (experimental and predicted)

695 initial zone due to the erosive effect of abrasive particles,
 696 which even seem to adhere to the thermoplastic matrix.
 697 However, the formation of fraying at the outflow of the water
 698 jet can lead to a deterioration of the surface quality of the
 699 material.

700 The combination of thermoplastic with carbon fiber rein-
 701 forcement can make machining difficult. It has been appreci-
 702 ated that the thermoplastic matrix does not separate from the
 703 composite and can alter the surface quality. However, the
 704 values of R_a obtained are very close to those of studies focused
 705 on thermoset matrix compounds. Also, it can be concluded
 706 that surface qualities suitable for industry are obtained without
 707 requiring secondary operations.

708 Finally, a combination of cutting parameters that minimizes
 709 R_a has been found by using a RSM, resulting on *hydraulic*
 710 *pressure* of 280 MPa, *abrasive mass flow* of 170 g/min, and a
 711 *traverse speed* of 100 mm/min, producing very smooth and
 712 homogeneous surfaces.

713 **Authors' contributions** F.B. and A.S. developed machining tests. M.B.
 714 and J.S. developed data treatment. F.B., A.S., M.B., B.S., and J.S. ana-
 715 lyzed the influence of the parameters involved. F.B. and A.S. collaborated
 716 in preparing figures and tables, and F.B., A.S., M.B., B.S., and J.S. wrote
 717 the paper.

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 722 University of Cadiz.

723 **Compliance with ethical standards**

724 **Conflict of interest** The authors declare that they have no conflict of
 725 interest.

726 **Nomenclature section** m , abrasive mass flow; ANOVA, analysis of
 727 variance; AWJM, abrasive water jet machining; CFRP, carbon fiber-
 728 reinforced plastics with thermoset matrix; CFRTP, carbon fiber-
 729 reinforced thermoplastics; EAZ, erosion affected zone; EDS, energy-dis-
 730 persive X-ray spectroscopy; P , hydraulic pressure; R_a , arithmetic mean
 731 roughness; RSM, response surface methodology; SEM, scanning electron
 732 microscope; TPU, thermoplastic polyurethane; UFFD, ultrafast feed drill-
 733 ing; UVD, ultrasonic vibration-assisted drilling; v , traverse speed

734
 735
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